

# A?

Aalto University

# Scordelis-Lo Roof Revisited

*Antti H. Niemi*

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# Shell Finite Elements

- The error estimates for *standard finite elements* for shells are of the form

$$\frac{||| \mathbf{u} - \mathbf{u}_{h,p} |||}{||| \mathbf{u} |||} \leq C \frac{L}{t} \left( \frac{h}{L} \right)^p$$

- There are formulations (like MITC-type) for which

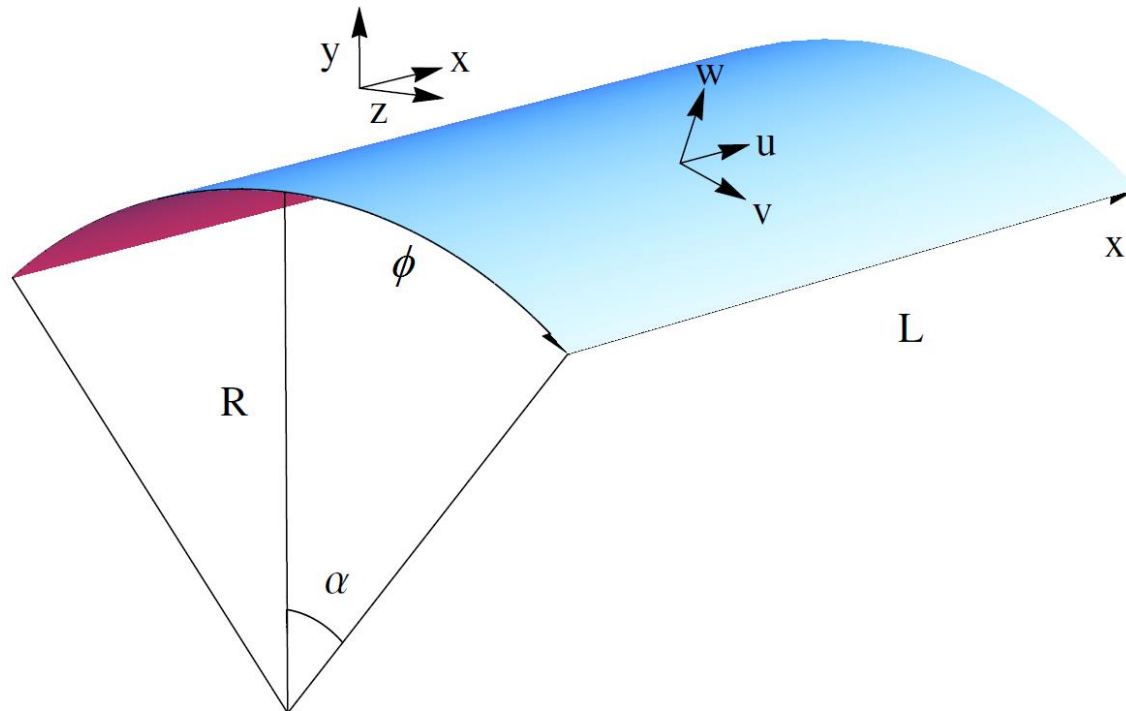
$$\frac{||| \mathbf{u} - \mathbf{u}_{h,p} |||_h}{||| \mathbf{u} |||} \leq C \left( \frac{h}{L} \right)^p$$

*under very specific geometric assumptions.*

- Practical shell finite element formulations are validated using *benchmark computations*

# Scordelis-Lo Roof Problem Setup

# Problem Setup (SI-units)



$$R = 25 \text{ m}$$

$$L = 50 \text{ m}$$

$$\alpha = 40^\circ$$

# Problem Setup (cont.) (SI-units)

- **Material:**
  - Isotropic material with Young's modulus set to  $E = 4.32 \cdot 10^8 \text{ N/m}^2$ .
  - Poisson's ratio set to  $\nu = 0.0$ .
- **Kinematic constraints:**
  - The outer curved edges are constrained against vertical translations (*diaphragm support*).
  - The outer straight edges are *free*.
- **Load:**
  - A force per are unit of  $-90 \text{ N/m}^2$  in the vertical direction is applied on the surface.

# Benchmark Setting

- **Set the thickness to  $t = 0.25$  m and determine the value of the vertical displacement at the center of the free edge.**
- **The reference solution quoted in the literature for the midside vertical displacement is  $-0.309$  m.**

**Scordelis, A. C., & Lo, K. S. (1964). Computer Analysis of Cylindrical Shells. *ACI Journal Proceedings*, 61(5).  
doi:10.14359/7796**

# Classical Shell Model (Love-Novozhilov-Koiter)

- **Total potential energy of the shell is**

$$\mathcal{F}(\mathbf{u}) = \frac{Et}{2} \int_{\omega} (\beta_{11}^2 + 2\beta_{12}^2 + \beta_{22}^2) dx d\phi + \frac{Et^3}{24} \int_{\omega} (\kappa_{11}^2 + 2\kappa_{12}^2 + \kappa_{22}^2) dx d\phi \\ - p \int_{\omega} (\sin \phi \cdot v - \cos \phi \cdot w) dx d\phi,$$

**where**  $\mathbf{u} = (u, v, w)$  **and**  $\omega = (0, L) \times (-\alpha, \alpha)$ .

- **The membrane strains are defined as**

$$\beta_{11} = \frac{\partial u}{\partial x}, \quad \beta_{22} = \frac{1}{R} \left( \frac{\partial v}{\partial \phi} + w \right), \quad \beta_{12} = \frac{1}{2} \left( \frac{1}{R} \frac{\partial u}{\partial \phi} + \frac{\partial v}{\partial x} \right)$$

# Classical Shell Model (cont.)

## Bending Strains

- **Shallow shell theory (LNK-SS):**

$$\kappa_{11} = \frac{\partial^2 w}{\partial x^2}, \quad \kappa_{22} = \frac{1}{R^2} \frac{\partial w}{\partial \phi^2}, \quad \kappa_{12} = \frac{1}{R} \frac{\partial^2 w}{\partial x \partial \phi}.$$

- **Novozhilov's model (LNK-S):**

$$\kappa_{11} = \frac{\partial^2 w}{\partial x^2}, \quad \kappa_{22} = \frac{1}{R^2} \frac{\partial w}{\partial \phi^2} - \frac{1}{R^2} \frac{\partial v}{\partial \phi}, \quad \kappa_{12} = \frac{1}{R} \frac{\partial^2 w}{\partial x \partial \phi} - \frac{1}{R} \frac{\partial v}{\partial x}.$$

- **Vlasov's model (Vlasov):**

$$\kappa_{11} = \frac{\partial^2 w}{\partial x^2}, \quad \kappa_{22} = \frac{1}{R^2} \frac{\partial w}{\partial \phi^2} + \frac{w}{R^2}, \quad \kappa_{12} = \frac{1}{R} \frac{\partial^2 w}{\partial x \partial \phi} - \frac{1}{2R} \frac{\partial v}{\partial x} + \frac{1}{2R^2} \frac{\partial u}{\partial \phi}.$$



# Semi-analytic Solution

# Ansatz

- **Kinematic constraints at  $x = 0, L$  are satisfied for**

$$u = \sum_{m=1}^{\infty} U_m(\phi) \cos(\beta_m x), \quad v = \sum_{m=1}^{\infty} V_m(\phi) \sin(\beta_m x), \quad w = \sum_{m=1}^{\infty} W_m(\phi) \sin(\beta_m x),$$

where

$$\beta_m = \frac{m\pi}{L}.$$

- **The constant load can be represented as**

$$p = \sum_{m=1}^{\infty} P_m \sin(\beta_m x), \quad P_m = \begin{cases} \frac{4p}{\pi m}, & m \text{ odd} \\ 0, & m \text{ even} \end{cases}$$

# Euler Equations Shallow Shell Theory

- Substitution of the Ansatz in  $\mathcal{F}(u)$  and minimization the energy with respect to  $U_m, V_m, W_m$  gives

$$\beta_m^2 U_m - \frac{\beta_m}{2R} V_m' - \frac{U_m''}{2R^2} = 0,$$

$$\frac{\beta_m^2}{2} V_m + \frac{\beta_m}{2R} U_m' - \frac{1}{R^2} (V_m'' - W_m') = \frac{P_m}{Et} \sin \phi,$$

$$\frac{1}{R^2} (V_m' + W) + \frac{t^2}{12} \left( \frac{W_m^{(4)}}{R^4} - \frac{\beta_m^2}{2R^2} W_m'' + \beta_m^4 W_m \right) = -\frac{P_m}{Et} \cos \phi.$$

- These constitute a system of *constant-coefficient* ODEs of total degree *eight*, valid when  $\phi \in (-\alpha, \alpha)$ .

# Natural Boundary Conditions Shallow Shell Theory

- The natural boundary conditions at the free edges  $\phi = \pm\alpha$  are

$$\begin{aligned}\frac{1}{R}U'_m + \beta_m V_m &= 0, \\ V'_m + W_m &= 0, \\ \beta_m^2 W'_m - \frac{1}{2R^2}W_m^{(3)} &= 0, \\ W''_m &= 0.\end{aligned}$$

- These correspond to the conditions of vanishing normal forces, effective shear force and bending moment.

# Solution

- **The solution of the system can be expressed as**

$$(U_m, V_m, W_m) = (\hat{U}_m, \hat{U}_m, \hat{U}_m) + \sum_{i=1}^8 C_i \mathbf{v}_i e^{\lambda_i \phi},$$

**where**

- $(\hat{U}_m, \hat{U}_m, \hat{U}_m)$  is a special solution of the *non-homogeneous* system.
  - $(\lambda_i, \mathbf{v}_i)$  are the eigenpairs associated to the *homogeneous* system.
- $(\hat{U}_m, \hat{U}_m, \hat{U}_m)$  **is found easily in the form**

$$(\hat{U}_m(\phi), \hat{U}_m(\phi), \hat{U}_m(\phi)) = (\tilde{U}_m \cos \phi, \tilde{V}_m \sin \phi, \tilde{W}_m \cos \phi)$$

# Solution (cont.)

- The special solution and the eigenvalues can be determined by symbolic computation for each  $m$ .
- The eigenvectors are solved numerically.
- The most difficult part is the determination of the integration coefficients  $C_i, i = 1, \dots, 8$ .
- These can be solved with Mathematica using arbitrary high numerical precision.

# Numerical Results

# Midpoint Vertical Displacement

- **Original problem setup with  $t=0.25$  m ( $R/t=100$ ):**

LNK-SS	LNK-S	Vlasov	COMSOL	MITC4S
-0.309 m	-0.299 m	-0.312 m	-0.302 m	-0.302 m

- **Academic problem setup with  $t=0.025$  m ( $R/t=1000$ ):**

LNK-SS	LNK-S	Vlasov	COMSOL	MITC4S
-30.9 m	-32.0 m	-32.0 m	-32.0 m	-32.0 m

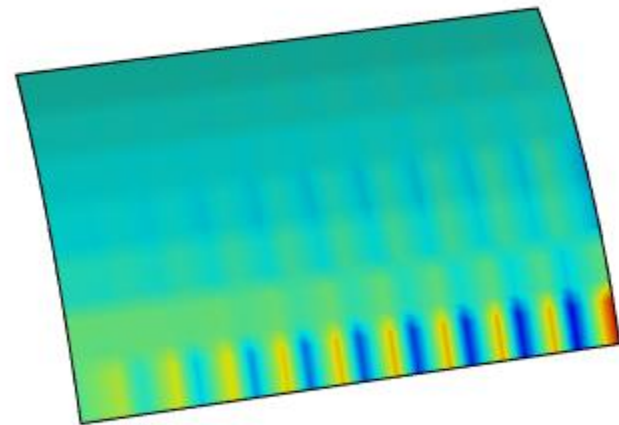
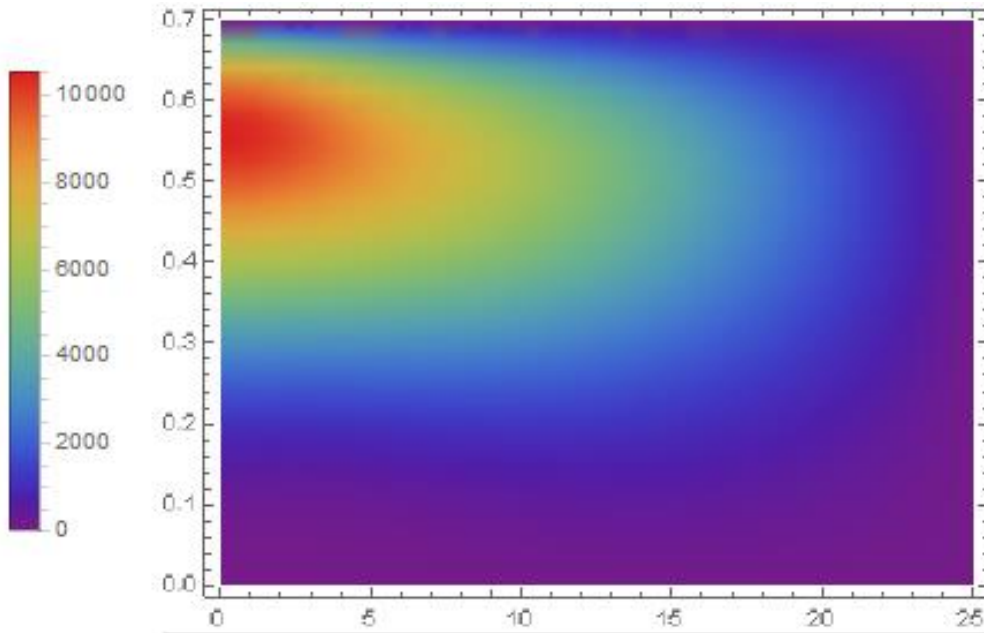


# In-plane Shear Force LNK-S vs. COMSOL (4-node, normal)

COMSOL  
MULTIPHYSICS

▲  $6.46 \times 10^4$   
 $\times 10^4$

6  
5  
4  
3  
2  
1  
0  
-1  
-2  
-3  
▼  $-3.77 \times 10^4$

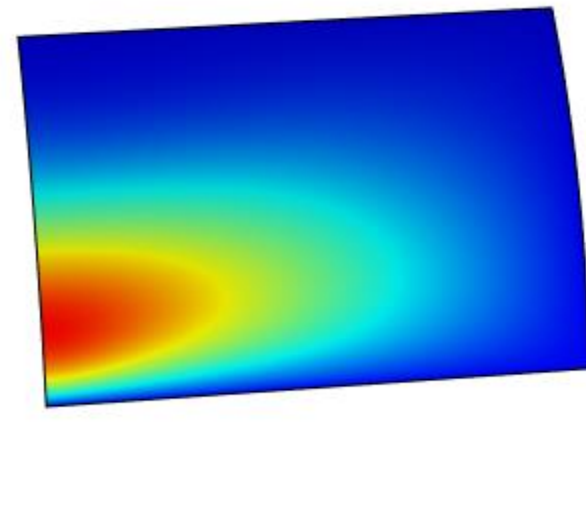
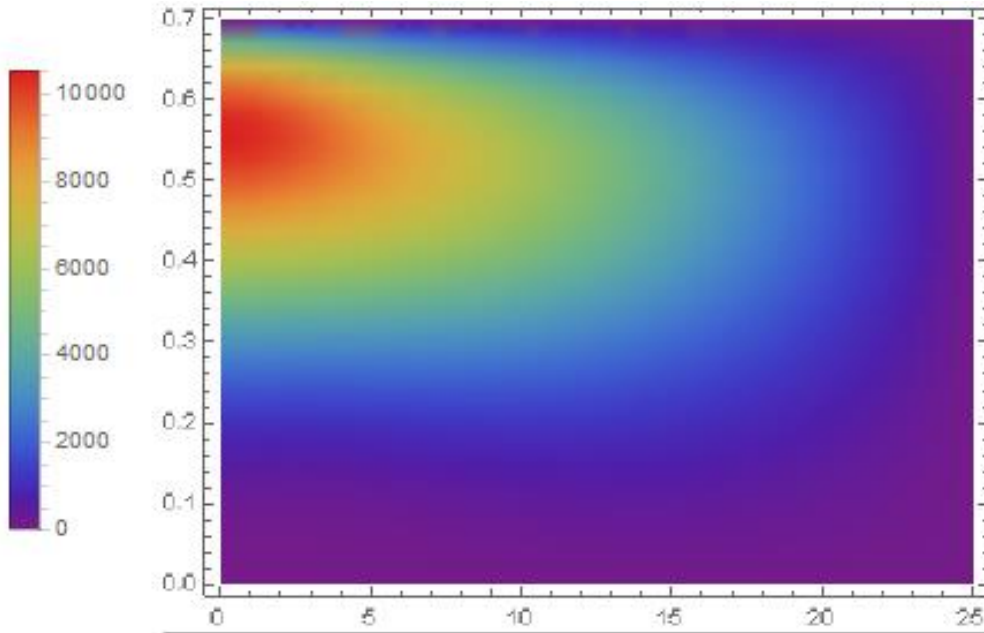


# In-plane Shear Force LNK-S vs. COMSOL (4-node, extra-fine)

COMSOL  
MULTIPHYSICS

▲  $1.07 \times 10^4$   
 $\times 10^4$

1  
0.9  
0.8  
0.7  
0.6  
0.5  
0.4  
0.3  
0.2  
0.1  
0  
▼ -36.2



# Concluding Remarks

- **We have presented a semi-analytic solution technique for the classical Scordelis-Lo roof model problem.**
- **Our approach allows to study different variants of shell models for different values of the thickness.**
- **The solution technique can be used to benchmark shell finite elements but also directly in the design of cylindrical shell roofs!**